

Notice of References Cited	Application/Control No. 10/596,048		Applicant(s)/Patent Under Reexamination TAKENAKA ET AL.	
	Examiner MCDIEUNEL MARC		Art Unit 3664	Page 1 of 1

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*		Document Number Country Code-Number-Kind Code	Date MM-YYYY	Name	Classification
*	A	US-2006/0214622	09-2006	Summer et al.	318/568.12
*	B	US-7,339,340	03-2008	Summer et al.	318/568.12
*	C	US-4,662,465	05-1987	Stewart, David E. S.	180/8.1
*	D	US-7,120,518	10-2006	Takenaka et al.	700/245
*	E	US-2002/0022907	02-2002	TAKENAKA et al.	700/245
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	L	US-			
	M	US-			

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NON-PATENT DOCUMENTS

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	V	Netto et al., Fuzzy systems to solve inverse kinematics problem in robots control: application to an hexapod robots' leg, 2000, IEEE, pg. 150-155
	W	Youcef et al., Control of the trajectory of a hexapod robot based on distributed Q-learning, 2004, IEEE, pg. 277-282
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*A copy of this reference is not being furnished with this Office action. (See MPEP § 707.05(a).)
Dates in MM-YYYY format are publication dates. Classifications may be US or foreign.